## Mechanical and Aeronautical Numerical Analysis



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### Agenda

- What is the Mesh Criteria?
- Mesh Free Method
- Mesh Free VS Mesh
- Conclusion



- Aspect Ratio The aspect ratio refers to the ratio of the longest edge to the shortest edge in the element. The aspect ratio significantly affects the analysis results, and a very small aspect ratio may lead to abnormal analysis results
- Skew Angle The skew angle refers to an angle deviating from the rectangular shape (90 degrees). Since two sides of a rectangle forms an angle of 90 degrees, the skew angle is 0, which is the most ideal value. The farther away from the shape of a rectangle, the higher the skew angle becomes (to a number greater than 0).





- Warpage The warpage refers to the state of deviation from a plane. If all the nodes of a 2D rectangular element are located on the same plane, the warpage is 0, which is the most ideal value. The farther away from the state of a plane, the greater the warpage angle becomes (to a number greater than 0).
- Taper The taper refers to the state of deviation calculated geometrically. Taper is not applicable to triangular elements. A rectangle retains the taper of 1, which is the most ideal value. The farther away from the shape of a rectangle (to the shape of a triangle), the smaller the taper becomes (to a number smaller than 1).





- Jacobian Ratio The Jacobian ratio refers to the ratio of the smallest Jacobian determinant to the greatest Jacobian determinant. The higher the Jacobian ratio, the better It is
- Twist Angle The twist refers to the state of twist between 2 opposing faces of a solid element
- Element Length Check the lengths of edges of an element. The minimum and maximum values can be specified



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#### Free Mesh





#### Free Mesh Steps

#### Analytical process (MeshFree)

Shorter overall analysis time compared to FEM method and high analysis success rate - Various post-processing functions for user convenience **STEP1** 

Direct CAD Interface (definition of material) STEP2

Definition of load/boundary conditions

#### **STEP3**

Analysis and results using state-of-the-art technology



#### What is Mesh Free

Mesh Free Methods use a set of nodes scattered within the problem domain as well as sets of nodes scattered on the boundaries of the domain to **represent** (not discretize) the problem domain and its boundaries.

No mesh implies no information on the relationship between the nodes is required.





### Mesh Free Support Domain

• Definition

The support domain for a point x is a sphere of a certain radius that relates to the nodal spacing near the point x.

#### • Reason

Determines the number of nodes to be used to approximate the function value at x.

• Restriction

The nodal density does not vary drastically in the problem domain.



#### Mesh Free Field Interpolation

The field variable u at any point x within the problem domain is interpolated using the values of this field at all the nodes within the support domain of x. Mathematically,

$$u(oldsymbol{x}) = \sum_{j=1}^n \phi_i(oldsymbol{x}) u_i$$





### Mesh Free Solving Equations

Numerical method depends on the kind of equations! Choices:

- Direct solver vs. iterative solver;
- Implicit method vs. explicit solver;
- Required accuracy;
- Speed of method;
- Stability of method;
- ...



#### Mesh Free Solving Flow Chart



![](_page_14_Picture_0.jpeg)

#### Mesh Free Nodal Generation

- The nodes must represent both problem domain and boundary
- The nodes can be chosen arbitrary within reason
- The node distribution can be uniform or not.

![](_page_15_Picture_0.jpeg)

#### **Mesh Free Function Properties**

• Partition of unity (compulsory condition)

$$\sum_{i=1}^{n} \phi_i(\boldsymbol{x}) = 1$$

• Linear field reproduction (preferable condition)

$$\sum_{i=1}^n \phi_i(oldsymbol{x}) x_i = oldsymbol{x}$$

• Kronecker delta function property (preferable condition)

$$\phi_i(oldsymbol{x}_j) = \left\{ egin{array}{cc} 1 & i=j \ 0 & i
eq j \end{array} 
ight.$$

![](_page_16_Picture_0.jpeg)

### Mesh Free MLS (Moving Least Square)

$$u^h(oldsymbol{x}) = \sum_{j=0}^m p_j(oldsymbol{x}) a_j(oldsymbol{x}) = oldsymbol{p}^T(oldsymbol{x}) oldsymbol{a}(oldsymbol{x})$$

#### with

$$\begin{aligned} \boldsymbol{p}^{T}(x) &= \left\{ 1, x, x^{2}, ..., x^{m} \right\} \\ \boldsymbol{p}^{T}(x, y) &= \left\{ 1, x, y, xy, x^{2}, y^{2}, ..., x^{m}, y^{m} \right\} \\ \boldsymbol{p}^{T}(x, y, z) &= \left\{ 1, x, y, z, xy, yz, xz, x^{2}, y^{2}, z^{2}, ..., x^{m}, y^{m}, z^{m} \right\} \end{aligned}$$

Features:

- finite series representation;
- ensures the approximated field function is continuous and smooth in the entire problem domain;
- capable of producing an approximation with the desired order of consistency.

![](_page_17_Picture_0.jpeg)

#### Mesh Free Residual Weight

 $u^h(oldsymbol{x},oldsymbol{x}_i) = oldsymbol{p}^T(oldsymbol{x}_i)oldsymbol{a}(oldsymbol{x})$ 

Weighted residual:

$$egin{aligned} J &= \sum_{i=1}^n W(oldsymbol{x} - oldsymbol{x}_i) [u^h(oldsymbol{x}, oldsymbol{x}_i) - u(oldsymbol{x}_i)]^2 \ &= \sum_{i=1}^n W(oldsymbol{x} - oldsymbol{x}_i) [oldsymbol{p}^T(oldsymbol{x}_i) oldsymbol{a}(oldsymbol{x}) - u_i]^2 \end{aligned}$$

![](_page_17_Figure_5.jpeg)

In MLS approximation, at an arbitrary point x, a(x) is chosen to minimize the weighted residual.

![](_page_18_Picture_0.jpeg)

#### Mesh Free Summary

- Mesh Free Methods are a respons to the limitations of Finite Element Methods.
- Mesh Free Methods do not use meshes, only nodes.
- The implementation of Mesh Free Methods differs from Finite Element Methods only in the shape function construction and node generation.
- The ideal Mesh Free Method is not found yet.

![](_page_19_Picture_0.jpeg)

# Thank You!

![](_page_19_Picture_2.jpeg)